

1 **Settlement under creep loading of an asphalt concrete in a railway structure.**
2 **Triaxial tests and viscoplastic modelling**

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8 **ABSTRACT**

9 SNCF Réseau and IFSTTAR are performing research to set up, in tunnels, new railway
10 structures using an asphalt concrete (AC) instead of ballast and sleepers. A PhD thesis started in
11 2016 on this topic, taking into account loading conditions of a railway for freight. The thesis is
12 linked to the French national project REVES.

13 The PhD thesis focuses on the creep triaxial behaviour of AC. A viscoplastic model of
14 Perzyna type is developed, made of a Drucker-Prager yield function closed with a cap model,
15 associated with a hardening function at one parameter. A procedure is developed to identify the
16 model parameters. Some structural simulations are then performed. They highlight some
17 characteristics of AC structures under heavy constant loadings. Amongst them, it is showed that
18 stresses redistribute in the structure over time leading to delete any tensile stress, like granular
19 materials. The first results seem to confirm that settlements of such a structure remain under the
20 maximum standard values imposed by SNCF.

21 **Keywords:** railways, Continuum mechanics, asphalt concretes, transient numerical
22 modelling, viscoplasticity.

23 **1. INTRODUCTION**

24 SNCF Réseau, the French railway board, and IFSTTAR, the French institute of science and
25 technology for transport development and networks, started a PhD thesis for studying innovative
26 ballastless railway infrastructures in tunnels. Tunnels rehabilitation is one current challenge of
27 SNCF Réseau. The collaboration consists in a PhD thesis proposed as part of the national project
28 “REVES” (translated "Reducing operated railways thickness in tunnels"). Innovation consists in
29 designing a very thin track, replacing the blanket layer, the ballast and the sleepers by an asphalt
30 concrete layer (AC). Despite this concept of AC track not being new, the settlement of AC due to
31 concentrated loads such as freight traffic is assessed here.

32 AC are well adapted to roadways, but freight railway traffic is heavier, slower and more
33 concentrated than truck traffic. Since the French method for designing road materials is well
34 established and standardized, new tools to consider this specific application in railway infrastructure
35 are needed.

36 The viscoplastic behaviour of AC under creep loads is studied and presented here. Based on
37 previous works and experimental tests [Soh11], a constitutive model is developed and fitted by
38 means of triaxial tests on a typical AC10 French asphalt concrete at different confining pressures
39 and deviatoric stresses, at 20°C. The protocol for fitting the parameters of the new viscoplastic
40 model is also presented in the next sections. Then, as the implementation of this Perzyna model in
41 Cast3m was set up, some transient viscoplastic structural calculations are achieved.
42 Displacements, stress and strain fields' evolution is assessed at the heart of railway structures in

1 asphalt mixes. Results highlights that the asphalt concrete tends to dissipate tensile and shear
 2 stresses and then to behave like an unbound material after a certain amount of loading time. This
 3 behaviour prevents from cracking, but leads to settlement in the structure. The first results show
 4 that calculated settlements of our virtual structure are less important than those authorized in the
 5 standard.

6 2. VISCOPLASTIC MODELLING

7 2.1 Conventions, Hypotheses, stress and strain invariants

8 The following hypotheses and conventions have been considered: small strains hypothesis elastic
 9 and viscoplastic strains are decoupled, only the VP evolution is considered for the hardening,
 10 strains can be expressed in percentage (%) and stresses are expressed in MPa.

11 Hydrostatic stress p and von Mises equivalent q stress, as well as volumetric strain ε_v and
 12 built deviatoric strain invariant ε_d can be written as follows, where $\underline{\underline{s}}$ is the deviatoric part of the
 13 stress tensor $\underline{\underline{\sigma}}$ and $\underline{\underline{e}}$ is the deviatoric part of the strain tensor $\underline{\underline{\varepsilon}}$:

$$14 \quad p = \frac{1}{3} tr \underline{\underline{\sigma}} \quad , \quad q = \sqrt{\frac{3}{2} (\underline{\underline{s}} : \underline{\underline{s}})} \quad , \quad \varepsilon_v = tr \underline{\underline{\varepsilon}} \quad \text{et} \quad \varepsilon_d = \sqrt{\frac{2}{3} (\underline{\underline{e}} : \underline{\underline{e}})}$$

15 The deviatoric strain was built so as to verify the following condition: $\underline{\underline{\sigma}} : \underline{\underline{\varepsilon}} = p \cdot \varepsilon_v + q \cdot \varepsilon_d$

16 2.2 Perzyna Viscoplastic model

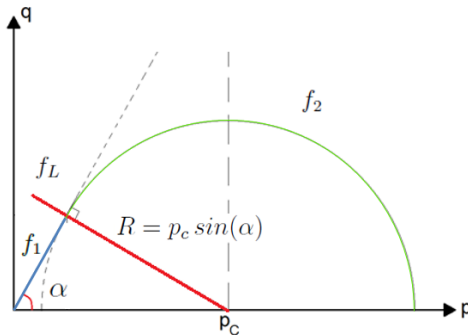
17 A standard associated Perzyna flow rule is used. The viscoplastic strain rate $\dot{\varepsilon}^{vp}$ is calculated as
 18 shown below. $\langle f \rangle$ is the positive part of the yield function f . η is a viscosity parameter and N is an
 19 experimentally-determined exponent.

$$20 \quad \underline{\underline{\dot{\varepsilon}}}^{vp} = \frac{1}{\eta} \langle f \rangle^N \frac{\partial f}{\partial \underline{\underline{\sigma}}}$$

21 The chosen yield is a Drucker-Prager cone associated to a spherical cap:

$$22 \quad f_1 = \cos(\alpha) q - \sin(\alpha) p \quad , \quad f_2 = \sqrt{(p - p_c)^2 + q^2} - p_c \sin(\alpha)$$

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FIGURE 1. Yield surface associated to the VP flow.
 A Drucker-Prager straight line closed by a circular cap model.

1 A “limit” function f_L is also considered: $f_L = q - \frac{1}{\tan(\alpha)} (p_c - p)$. The line $f_L = 0$ passes
 2 through the center of the circle and the tangent point between f_1 and f_2 .
 3 If $f_L \leq 0$, then $f = f_1$. If $f_L > 0$, then $f = f_2$.

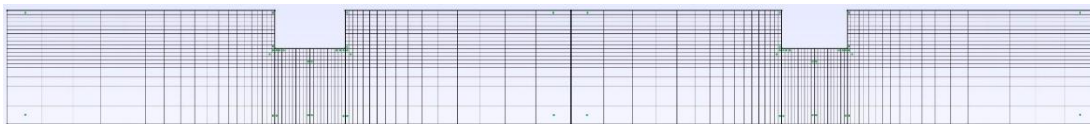
4 A set of parameters was identified by means of the triaxial tests carried out in a previous
 5 study [Soh11]. The identification is made in several steps described here: setting N, the power of
 6 the function (imposed to 1 or 2 at the moment), setting p_{c0} , to start the test at constant volume,
 7 setting $a = \tan(\alpha)$, the DP slope, corresponding to the tests able to stabilize, setting b, maximum
 8 strain reached for any test and Setting η the hardening parameter to fit with the kinetic of the strain
 9 curves

10 TABLE 1. A first set of parameters.

| Parameter | Value |
|-----------|-------|
| N | 2 |
| a | 2.4 |
| pc0 | 0.16 |
| b | 1.4 |
| η | 12 |

11 **2.3 Implementing Perzyna in the FEM code Cast3m**

12 The Perzyna law was implemented in Cast3m as a user law. Simulations on a single finite
 13 element were performed to validate the implementation. A basic 2D structural simulation was also
 14 carried out in order to simulate a punching test of an asphalt concrete slab under a heavy static
 15 load. Strains and stresses were analysed on elements located in critical zones of the AC. The
 16 theoretical behaviour law was respected with an error lower than 1% on every element analysed,
 17 which are represented by green dots on FIGURE 2. It can thus be concluded that the model was
 18 correctly implemented into Cast3M.
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 21 FIGURE 2. Validation of the numerical implementation on a 2D structural simulation

22 **3. CREEP SIMULATIONS ON AN INNOVATIVE RAILWAY STRUCTURE**

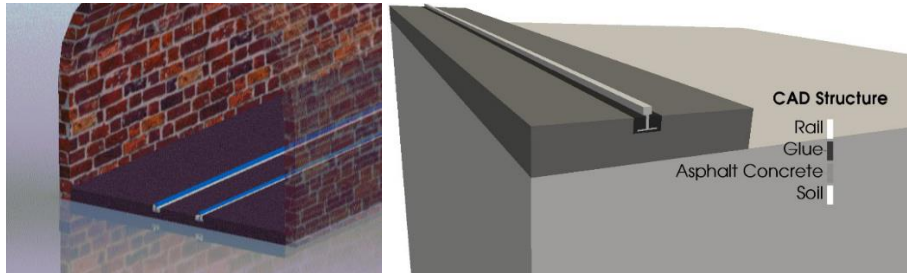
23 **3.1 Using Gmsh to Parameterize the design**

24 Gmsh [GR09] is a 3D finite element mesh generator with built-in pre- and post-processing
 25 facilities, distributed under the terms of the GNU General Public License (GPL). In this study,
 26 only Gmsh pre-processor tools were used. Firstly, the railway structure geometry was designed in
 27 a parameterized manner, so that most of the dimensions can easily be modified for further
 28 optimizations. Once the geometry was defined and saved (‘file.geo’), the mesh was generated and
 29 saved in ‘universal’ format (‘file.unv’), which allowed it to be readable by Cast3m for further FEM
 30 calculations. Meshing can also be parameterized to densify elements’ sizes close to the point of
 31 load application as well to choose the type of element (tetrahedron, cube, etc). Any kind of

1 geometric entity can be saved as a physical group, simplifying the application of boundary
2 conditions, loads, and further analysis.

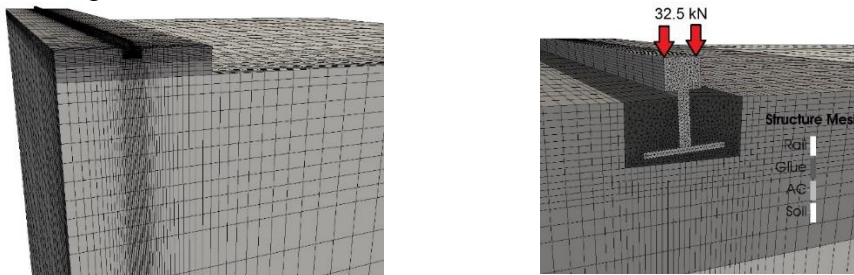
3 3.2 Structural design of the Railway structure

4 Considering the specifications of the REVES project, a first ballastless railway structure has
5 been designed. First numerical simulations were performed with previous viscoplastic models
6 during B. Mazaheri's internship at IFSTTAR [Maz16]. The structure has been subjected to a heavy
7 static load representing a freight train stopped on the track for a long time (300 years).
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10 FIGURE 3. (a) REVES Railway structure in a tunnel (concept).
11 (b) $\frac{1}{4}$ structure with soil and without the tunnel for further computations.
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13 In order to limit computation times, only one rail has been modelled. The two vertical
14 symmetry plans have been used as shown in FIGURE 3(b). Due to these symmetries, the applied
15 force is one fourth of the total force exerted by the wheel on the rail, 32.5 kN. A line force is
16 applied on the edge of the rail as shown in FIGURE 4(b).



17
18 FIGURE 4. (a) Meshing
19 (b) Zoom on the AC layer and rail.

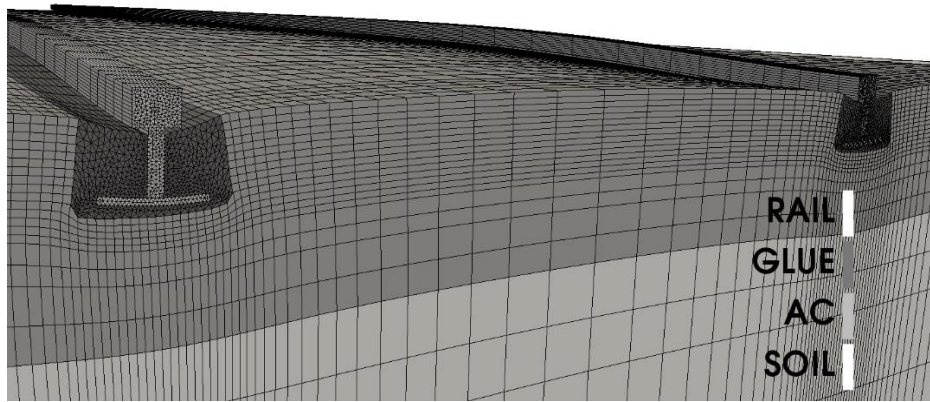
19 4. CREEP SIMULATIONS RESULTS

20 4.1 Displacements, strains, vertical settlement

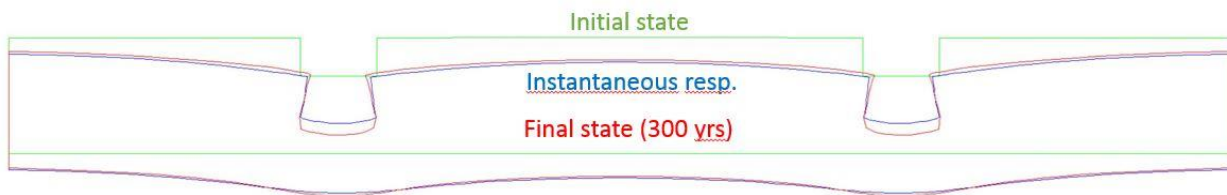
21 Results of the creep 3D simulation on the railway structure are partially presented in
22 **Erreur ! Source du renvoi introuvable.**(a), where the deformed structure is shown, with an
23 amplification factor of 100. This first figure shows, under the rail, a settlement of the soil under
24 the asphalt concrete, a deformation of the bottom of the groove in the vertical section, and also a
25 deformation of the rail.

26 The maximum vertical displacement of the rail after 300 years of simulation is 1.56 mm.
27 The maximum acceptable irreversible displacement of 3.0 mm is given by SNCF levelling
28 standards.

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4 **FIGURE 5. (a) Deformed structure at the end of the simulation (amplified 50 times).**
 5 **(b) Evolution of the asphalt concrete section with time.**

6 A view of the deformed Asphalt concrete section at initial time step, just after loading and
 7 at final time step is presented in FIGURE 5(b). The immediate response is the elastic response, it
 8 corresponds to a global settlement of the soil. The viscoplastic response at final step leads to a
 9 settlement more localized under the groove, under the load and the rail.

10 **4.2 Vertical stresses in the vertical section under the load**

11 The evolution of the vertical stress between the initial and the final time step is presented in
 12 FIGURE 6. Initial tensile stress is very low in the vertical direction, and tends to completely
 13 disappear with time. The compressive stress, strongly concentrated under the middle of the groove,
 14 finally spreads under the groove and beyond.

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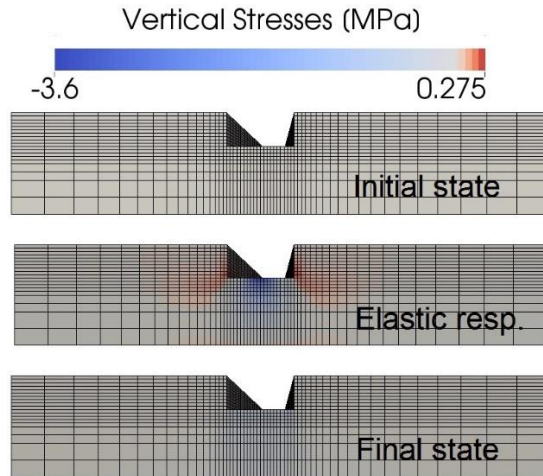


FIGURE 6. Vertical stress inside the AC layer at initial and final time steps.

4.3 Horizontal tensile strains and stresses

Horizontal stresses and strains are presented in **Erreur ! Source du renvoi introuvable.** Three different time steps are selected for the analysis: the initial step “0”, the step one, which mostly corresponds to the immediate response of the structure and the final step (300 years). The horizontal stress shows initial compression at the bottom of the groove and traction at the bottom of the AC layer. At the final time step, all horizontal tensile stress disappears. The horizontal strains at step 1 shows a kind of beam in flexion. At the final step, tensile strains reach $100\mu\text{def}$ under the groove, while compression is concentrated at the corners of the groove. These strains can be considered as acceptable for long term strains.

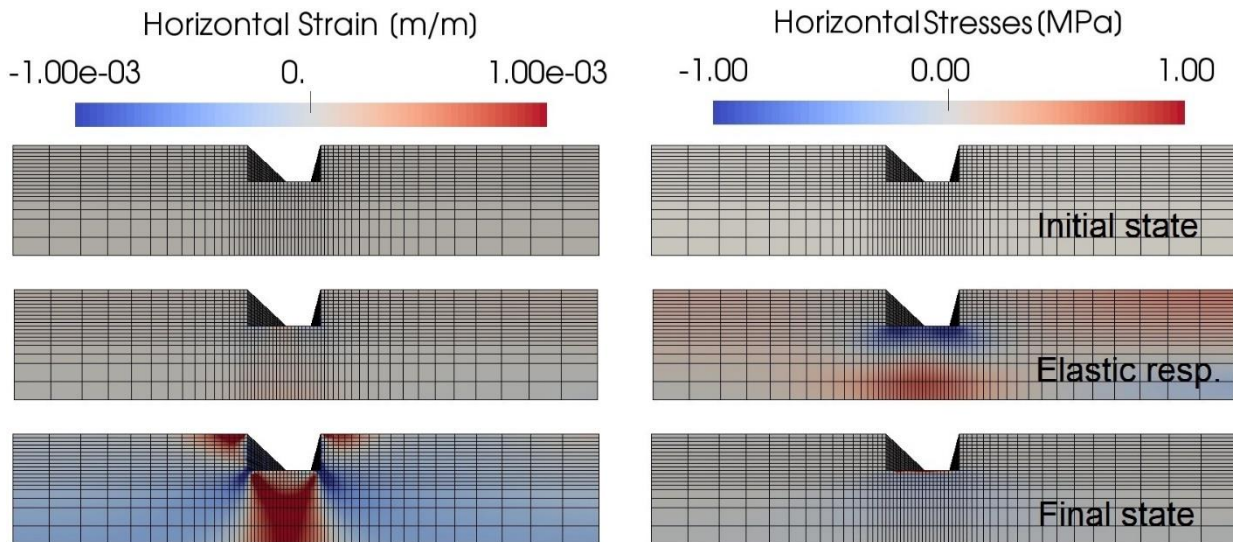


FIGURE 7. Horizontal strain (a) and stress (b) states during the creep test.

1 **5. CONCLUSIONS AND OUTLOOK**

2 The first results obtained showed a coherent response of our viscoplastic model. The
3 deformed structure presents a correct shape. The order of magnitude of displacements, the
4 stabilizing creep and the “bump” near the loaded region all are representative of real asphalt
5 concrete behaviour. Stress states in the bituminous mixture evolve in such a way that tensile
6 stresses tend to disappear. Stabilization in creep is due to the evolution of stresses from a bending
7 beam state to that of an unbound soil without any tensile stresses. Further studies will be needed
8 to determine how representative this is and whether this interesting result comes from the
9 constitutive model's construction or from the numerical computation. The results obtained from
10 the first 3D railway structure simulations show acceptable displacements in the case of a creep
11 loading, such as a train stopped on the track for a long period of time could generate. Once again,
12 tensile and shear stresses tend to disappear over time. These first results also need to be confirmed.

13 The next steps of this work include experimental tests, to be performed in order to determine
14 model parameters for a bituminous mixture that would be used in the REVES project. This will
15 allow us to verify the viability of the various ballastless track concepts that will be developed.
16 Furthermore, simple structural experimental creep tests will be performed in order to assess the
17 accuracy of the model outside of a homogeneous triaxial test. Afterwards, rutting and fatigue
18 resistance will be taken into account to improve structural design.

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