Calibration of Mechanistic-Empirical Fatigue Models Using the PaveLab Heavy Vehicle Simulator

- Eliecer Arias-Barrantes¹, José Pablo Aguiar-Moya², Luis Guillermo Loría-Salazar³, Edgar Camacho-Garita⁴
 (¹ LanammeUCR, University of Costa Rica, San José, eliecer.arias@ucr.ac.cr)
 (² LanammeUCR, University of Costa Rica, San José, jose.aguiar@ucr.ac.cr)
 - (³ LanammeUCR, University of Costa Rica, San José, Juis.loriasalazar@ucr.ac.cr.)
- 8 (⁴ LanammeUCR, University of Costa Rica, San José, edgar.camachogarita@ucr.ac.cr)

9 ABSTRACT

7

10 In Costa Rica, pavement design has been traditionally based on empirical methods such as AASHTO 93, which was originally developed several decades earlier and is based on the 11 12 AASHO road test. It is important to note that the method was calibrated for conditions that 13 significantly differ from tropical climates. For this reason, the National Laboratory of Materials and Structural Models of the University of Costa Rica (LanammeUCR) has 14 actively worked on research projects with the objective of incorporating the fundamental 15 principles of engineering to pavement design. To achieve this goal, an Accelerated Pavement 16 Testing (APT) program was established in 2012: PaveLab. The program relies on a Heavy 17 Vehicle Simulator (HVS) as a tool to assess full scale performance of pavement structures. 18 19 Four full-scale test pavement structures with different configurations (materials and 20 thicknesses) have been constructed in the PaveLab, for a total of 8 test sections that will allow the analysis of the behavior of materials under different structural and humidity 21 22 conditions. All the test tracks were instrumented and are continuously monitored. The 23 analysis and correlation between the laboratory results and the performance observed in the 24 different test section will allow the calibration of fatigue damage models for different kinds 25 of pavements.

26

Keywords: HVS, Accelerated, Pavement, LanammeUCR, APT

27

28 **1. INTRODUCTION**

Important progress in pavement engineering have been traditionally achieved through real time load (RTL) testing since the technique does not require large specialized equipment for carrying out the test. However, significant time is required (more than 10 years of continuous monitoring for a given experimental section). In Central America, there is a great need to characterize the performance of pavement structures as the only means of developing and calibrating design methodologies. For this purpose, the implementation of an Accelerated Pavement Testing (APT) program was considered a better alternative (1).

36 To attend this need, a Costa Rican APT program was implemented (PaveLab), relying on a Heavy Vehicle Simulator (HVS) since it was considered the best option for the local and 37 38 regional needs. Specifically, the PaveLab had to meet the following requirements: mobility, 39 accelerated pavement evaluation, application of real loads, and comparable results to similar equipment (2, 3, 4). To evaluate the effect of moisture on pavement performance, pavement 40 structures with different types of base, and under different humidity conditions in the lower 41 42 layers have been analysed. Currently, PaveLab aims to generate a series of products that have 43 already been obtained under similar studies but for different conditions (5, 6, 7):

44 45 • Mechanistic-empirical pavement design methodology and software based on material conditions, weather, traffic and actual construction practices.

1	• Development of new material specifications based on actual performance and
2	contribution of structural materials in the field.
3	• Optimization of pavement structures in use at the national level, based on
4	structural, materials, traffic, and climatic conditions specific to the area where
5	the structure is planned to be built.
6	• Potential for an improved evaluation methodology of new materials or
7	materials currently in use.
8	• Capacity to evaluate pavement structures of high importance prior to opening
9	to traffic to ensure the required performance of the structures or identify
10	possible deficiencies.

11 2. PAVELAB TEST SECTIONS

12 The initial set of experiments performed at PaveLab corresponds to four structures 13 shown in Figure 1 and detailed in Table 1. The test tracks AC4 and AC3 are under 14 investigation, for this reason, are excluded to this analysis.





18

FIGURE 1 Test track distribution

TABLE 1 Test tracks in-place properties after construction

Section	001AC1	003AC2	008AC1	007AC2
Properties				
AC Thickness (H1), cm	6.1	6.3	6.1	6.3
Base Thickness (H2), cm	21.9	21.2	21.9	21.2
Subbase Thickness (H3), cm	30.1	30.1	30.1	30.1
AC Modulus (E1), MPa [@ 25 °C, 1.5 Hz]	3500	3500	3500	3500
Base Modulus (E2), MPa	1200	115	1750	300
Subbase Modulus (E3), MPa	142	75	500	100

19

1 The CTB layer has a 3MPa of compressive strength at 7 days. The HMA has a 5 % of asphalt 2 content as percent of the mass of the oven-dry total aggregate. The granular base and subbase 3 is river coarse material, crushed and well graded. The subgrade is a cohesive soil, with high 4 plasticity.

5 3. INSTRUMENTATION

6 The measurements were performed using the HVS integrated instrumentation and 7 embedded sensors in all four test sections. HVS onboard instrumentation records different 8 signals: the applied load, tire pressure and temperature, position and velocity of the load 9 carriage. Embedded sensors included asphalt strain gauges, pressure cells, multi-depth deflectometers (MDDs), and moisture and temperature probes. The HVS was equipped with 10 a laser profiler that can be used to recreate a three-dimensional profile of the section. 11 12 Additionally, a road surface deflectometer (RSD) was used to obtain deflection basins at any 13 location along the test section. Figure 2 shows the typical instrumentation array used for the 14 experiments.

15



16 17

FIGURE 2 Sensor array used for each test track

18

19 Data collection of the 3D profile, strain, pressure, temperature, and deflection was 20 performed based on load repetitions. At the beginning of each test, data was obtained at short 21 intervals: 1,000, 2,000, 5,000, and 10,000 loads repetitions. After 20,000 load repetitions, 22 data is collected on daily basis. Inspection of fatigue and reflective cracking, friction loss, loss of aggregate-asphalt bond, and any other surface deterioration is performed on daily 23 24 basis during the HVS maintenance check. Finally, International Roughness Index (IRI) was 25 calculated by means of a quarter-car vehicle math model for each of the longitudinal data 26 lines: the transverse measurements are independent.

27 **4. SATURATION OF THE TEST TRACKS**

The humidity levels were strictly controlled to maintain a constant water table at 70 cm from the pavement surface, which allows to maintain saturation levels in the subgrade at approximately 87% (the optimum dry density of this soil is achieved at 80% saturation, equivalent to an optimum humidity of 55%). For base and subbase layers, the saturation level was controlled at approximately 43%. To regulate the water table, the saturation chamber has an automated system to ensure the optimal flow of water to maintain stable humidity conditions.

35 **5. PROPOSED FATIGUE MODEL**

Damage functions can be used for modelling cracking of bound materials, permanent
 deformation and roughness for all layers. A general damage function can be expressed as
 follows (8).

1

$$Damage = A \times MN^{\alpha} x \left(\frac{resp}{resp_{ref}}\right)^{\beta} x \left(\frac{E}{E_{ref}}\right)^{\gamma} x e^{\delta T}$$
(1)

2 Where MN = the number of load repetitions (ESAL) in millions, resp = the response 3 (stress or strain), $resp_{ref}$ = a reference response (can be related to strength), E = the modulus 4 of the material (adjusted for climate and damage), E_{ref} = a reference modulus, and A, α , β , 5 and γ are model constants.

6 For bound materials, structural damage may be defined as the relative decrease in 7 modulus (the decrease in modulus -dE- relative to the initial modulus -Ei-). During early 8 stages in the service life of a layer, the decrease in modulus will primarily be due to micro 9 cracking that will later evolve into macro cracking. The process is complex and using the 10 average modulus of the layer is not considered adequate.

11 **6. RESULTS**

12 6.1 Four Point Bending Beam (4PBB) Fatigue Tests

Tests were performed for laboratory produced and plant asphalt mixes to the number of load repetitons required to reach 50% stiffness reduction as function of tensile strain at different temperatures. Tests were completed according to AASHTO T 321 under constant strain loading at three strains levels 400, 600 and 800 microstrain and three test temperatures (10, 20 and 30 °C) (17).

Damage of the asphalt mixture was defined as the relative decrease in modulus dE relative to the initial modulus Ei for each sample; this was used to calibrate the model shown in Eq.(2). Equation parameters were determined from 4PBB strain controlled samples, by minimizing Root Mean Square (RMS) of the difference between measured and calculated damage from Eq. (1).

23

29

$$\omega = 0.189 \times (MN)^{0.271} \times \left(\frac{\varepsilon}{200}\right)^{1.07} \times \left(\frac{E}{3000}\right)^{0.535} \times e^{(0.035T)}$$
(2)

24 Where MN= the number of load repetitions in millions, ε = tensile micro strain, E= 25 material modulus, T= temperature.

The initial calibration corresponds to apply a 1.4 adjustment factor to Eq.(2). This factor was generated with preliminary HVS data analyzes of thick layers sections and dry conditions, from a previous work (9).

30 6.2 Backcalculated Layer Moduli

RSD deflection data was used to determine the progression of the pavement layer moduli through backcalculation. The backcalculation was based on the method of equivalent thickness (MET) where the thickness of the different layers is transformed into an equivalent single layer, which is based on Odemark's methodology. Stress, strains and deflections calculation was realized using Boussinesq theory (10).

Damage was determined for the laboratory tests as well as for each individual test section at five different locations. Three deflection measurements were performed at each location. Therefore, it was possible to determine strain responses based on Layered-Elastic Theory and verified these with strain gauges embedded in each track. In addition to estimation of damage, temperature records at mid depth of the asphalt layer were also recorded to correct the modulus of the temperature-susceptible layers.

Damage to asphalt concrete was estimated to evaluate how the laboratory model relates
 to the APT results. This correction was performed using factors to shift the damage between

laboratory and field conditions. The different conditions for each test track indicate that a
 single adjustment factor might not be adequate for predicting fatigue damage. Consequently,
 independent calibration factors for each test were developed: granular base, CTB, optimal
 humidity or high degree of saturation in subgrade.

5 Differences from 100% to 150% in damage were observed between the four point 6 bending beam (4PBB) laboratory model and the 003AC2-Dry APT test section (based on 7 measured values of maximum strain at the bottom of the HMA layer). On the other hand, 8 there is a 6% difference between the damage values predicted from 4PBB data and real 9 damage measured in section 007AC2-Wet. However it has to be considered that the section 10 failed early at 450,000 equivalent axles.

For pavements with CTB layer, the predicted damage with the 4PBB regression considerably underestimates the damage, the CTB layer causes initial strains at the bottom of HMA layer to be low. These pavement structures show significantly less damage when the experiment was completed.

Equation 3 is obtained by transforming equation 2 into a classical fatigue function. The models were calibrated for the strain level measured at the bottom of the HMA for each section, at three damage levels between 60% and 90%.

$$MN = k_1 * \left(\frac{\varepsilon}{200}\right)^{-k_2} * \left(\frac{E}{3000}\right)^{-k_3}$$
(3)

18 19

20

where k_1, k_2, k_3 and k_4 = regression coefficients corrected with HVS data.

If equation 2 is transformed in a classical fatigue function, the model defined in equation 3 is obtained, and the respective calibration coefficients are shown in Tables 2 and 3. The coefficients were calibrated for three damage levels, since loading for the four test tracks was stopped when damage levels reached the range between 60% and 90%. In addition, the models were calibrated for the strain level measured at the bottom of the HMA for each section. In the case of the pavement with CTB the strain was 15 $\mu\epsilon$ and in the pavement with granular base was 353 $\mu\epsilon$.

28

 TABLE 2 Calibration parameters for thin HMA layer over CTB.

Section AC1 Dry conditions				Section AC1 Wet conditions			
	Damage level			Coofficients	Damage level		
Coefficients	60%	70%	90%	Coefficients	60%	70%	90%
k1	0.040	0.061	0.124	K ₁	0.004	0.006	0.012
k ₂		-3.006		K ₂		-2.784	
k3		-1.503		K ₃	-1.392		
k4	-0.099			K 4	-0.092		

29

 TABLE 3 Calibration parameters for thin HMA layer over granular base.

Section AC2 Dry conditions				SectionAC2 Wet conditions			
	Damage level			Coofficients	Damage level		
Coefficients	60%	70%	90%	Coefficients	60%	70%	90%
K_1	276.892	425.623	857.887	K_1	10.161	15.784	32.365
K ₂	-2.983		K ₂	-3.056			
K ₃	-1.492		K ₃	-1.528			
K_4	-0.098		K_4	-0.100			

1 Three levels of damage are calculated in the models because these levels of damage were

2 shown during the test, it's very important clarification that the failure criteria and the criteria

3 to stop the test are two conditions very different, associated directly to the type of structure.

4 7. CONCLUSIONS

5 The generated fatigue models account for different conditions in terms of materials 6 and humidity for pavements with a thin HMA layer. Throughout the present project, it was 7 verified that the 4PBB regression equation does not adequately match with the f full-scale 8 accelerated pavement test performed on HMA thin layer sections. For this reason is very 9 important a field calibration, under different humidity conditions and different pavements 10 structures. Furthermore, in the future other conditions must be considered to validate the 11 results obtained in this tests.

The calibration of the fatigue model coefficients between 4PBB and APT sections shown in Tables 2 and 3 are satisfactory for each of the test tracks. Different calibration parameters were required for each section since the behaviour for each test condition was different, mainly for the test tracks with CTB layer under higher humidity levels.

16 The currently undergoing tests will allow the analysis of the behaviour of thick HMA 17 layers under different humidity conditions.

18 The fatigue models were calibrated for strain levels corresponding to the pavements 19 shown in Table 1 (AC1 and AC2). Future tests sections will expand the strain level range.

20 7. REFERENCES

25

26

27

31

32

40

41

- Aguiar-Moya, J.P., Corrales, J.P., Elizondo, F., and Loría-Salazar, L. PaveLab and Heavy Vehicle Simulator Implementation at the National Laboratory of Materials and Testing Models of the University of Costa Rica. Advances in Pavement Design through Full-scale Accelerated Pavement Testing, pp 25-33. 2012.
 - Coetzee, N et al. The Heavy Vehicle Simulator in Accelerated Pavement Testing: Historical Overview and New Developments. 3rd International Conference APT. 2008.
- Harvey, J. T., Hoover, T., Coetzee, N. F., Nokes, W. A., and Rust, F. C. Caltrans
 Accelerated Pavement Test (CAL/APT) Program—Test Results: 1994–1997. AAPT
 Symposium on Accelerated Pavement Testing, Boston, MA, March 16-18, 1998.
 - 4. Leiva, Aguiar y Loría. Ensayos Acelerados De Pavimentos En Costa Rica. RevistaInfraestructura Vial, Vol 15 (#26), 33-41. San José Costa Rica, 2013.
- 5. Harvey, J. T., L. du Plessis, F. Long, S. Shatnawi, C. Scheffy, B-W. Tsai, I. Guada, D.
 Hung, N. Coetzee, M. Reimer, and C. L. Monismith. Initial CAL/APT Program: Site
 Information, Test Pavement Construction, Pavement Materials Characterizations,
 Initial CAL/APT Test Results, and Performance Estimates. Report prepared for the
 California Department of Transportation. Report No. RTA-65W485-3. Pavement
 Research Center, CAL/APT Program, Institute of Transportation Studies, University
 of California Berkeley. 1996.
 - 6. Timm, D. NCAT Report 09-01 Design, Construction And Instrumentation Of The 2006 Test Track Structural Study, NCAT. 2009.
- 42 7. Leiva-Villacorta, F. and D. Timm, Analysis of Measured Versus Predicted Critical
 43 Pavement Strain Responses, Proceedings of the 90th Annual Transportation Research
 44 Board, Washington, D.C. 2011.
- 8. Ullidtz, P., Harvey, J.T., Tsai, B-W. and Monismith, C.L. "Calibration of Mechanistic-Empirical Models for Flexible Pavements Using the WesTrack Experiment", AAPT, 2008.

- 9. Leiva-Villacorta, F., Vargas-Nordcbeck, A. Aguiar-Moya, J.P., Loría-Salazar, L.G.
 Calibration of a Mechanistic-Empirical Fatigue Model Using the PaveLab Heavy
 Vehicle Simulator. Transportation Research Board 95th Annual Meeting Proceedings.
 Washington, D.C. 2016.
- 10. Ullidtz, Per, "Will Nonlinear Backcalculation Help?," NondestructiveTesting of
 Pavements and Backcalculation of Moduli: Third Volume. ASTM STP 1375, S. D.
 Tayabji and E. O. Lukanen, Eds., American Society for Testing and Materials, West
 Conshohocken, PA, 2000.